

P1025RDB-PA Specification

QorIQ Integrated Communications Processor

The reference design board (RDB) is a system featuring the P1025E QorIQ processor, which includes a built-in security accelerator and QUICC Engine. This low-cost, high-performance system solution consists of a printed circuit board (PCB) assembly and a software board support package (BSP). This BSP enables the fastest possible time-to-market for development or integration of applications including printer engines, broadband gateways, no-new-wires home adapters/access points, and home automation boxes.

This document describes the hardware features of the board including specifications, block diagram, connectors, interfaces, and hardware straps. It also describes the board settings and physical connections needed to boot the RDB. Finally, it considers the software shipped with the platform.

When you finish reading this document, you should be familiar with:

- The board layout and its interfaces
- The board configuration options
- How to get started and boot the board

Contents

1	Introduction	2
2	P1025RDB Hardware	2
3	Memory Interface	7
4	SerDes Interfaces (PCIe/SGMII)	8
5	Enhanced Local Bus Controller (eLBC) Interface	9
6	Ethernet	12
7	eSPI	16
8	eSDHC Interface	17
9	GPIO	18
10	I ² C	18
11	USB Interface	20
12	Dual RS-232 Ports	21
13	Lattice PLD	23
14	POR Configuration	23
15	JTAG/COP	23
16	Interrupts	25
17	DMA	26
18	RS485	26
19	PMC	26
20	Connectors, Headers, Push Buttons and LEDs	28
21	Power Related	31
22	1588	33
23	Clocking	33
24	Reset	33
25	Switch Settings	33
26	Getting Started	40
27	Revision History	43

This document contains information on a product under development. Freescale reserves the right to change or discontinue this product without notice.

© Freescale Semiconductor, Inc., 2011. All rights reserved.

Agile # UMS-26826



1 Introduction

This document is applicable for PCBA Rev2.0 and PLD Rev2.6. The revision information is shown in the log file of board booting.

1.1 Acronyms and Abbreviations

Table 1 lists commonly used acronyms and abbreviations.

Table 1. Acronyms and Abbreviations

COP	Debug Port in Powerpc	PHY	Physical Layer Interface Device
DDR	Double Data Rate DRAM	PLL	Phase Lock Loop
LYNX	High Speed Serial Interface	SERDES	Serializer/Deserializer
PCIe	PCI Express®	USB	Universal Serial Bus
QE	QUICC Engine	TDM	Time Division Multiplex

1.2 Reference Documents

The following documents are available on Freescale's intranet library.

- P1025E QorIQ Integrated Processor Family Reference Manual
- P1025E QorIQ Integrated Processor Hardware Specification

2 P1025RDB Hardware

This section covers the features, block diagram, specifications, and mechanical data of the RDB.

2.1 P1025E Features

The board features are as follows:

- P1025E running at 533 MHz, platform 266 MHz, DDR3 667 MHz
- Memory subsystem:
 - 1Gbyte unbuffered DDR3 SDRAM discrete devices (32-bit bus)
 - 16 Mbyte NOR flash single-chip memory
 - 32 Mbyte NAND flash memory
 - 256 Kbit M24256 I2C EEPROM
 - 16 Mbyte SPI memory
 - SD connector to interface with the SD memory card
- Interfaces:
 - PCIe
 - x1 PCIe slot
 - x1 mini-PCIe slot

- 10/100/1000 BaseT Ethernet ports:
 - eTSEC1, RGMII: one 10/100/1000 port using Atheros™ AR8021
 - eTSEC2, SGMII: one 10/100/1000 port using Vitesse™ VSC8221
 - eTSEC3, RGMII: one 10/100/1000 port using Atheros™ AR8021
- 10/100 BaseT Ethernet ports:
 - UEC1,MII: one 10/100 port using Micrel™ KSZ8041
 - UEC5,RMII: one 10/100 port using Micrel™ KSZ8041
- USB 2.0 port:
 - ULPI PHY interface: SMSC USB3300 USB PHY and Genesys Logic's GL850A USB2.0 HUB Controller with 4 downstream ports
 - Two USB 2.0 Type A receptacles
 - One USB 2.0 signal to Mini PCIe slot
- Dual RJ45 UART ports:
 - DUART interface: Supports two UARTs up to 115200 bps for console display
- Two 10-Pin RJ45 RS485 ports
 - Both ports are full duplex mode
- Board connectors:
 - Open frame power supply connector
 - JTAG/COP for debugging
 - PMC connector
 - UMI(PLC)connector
- IEEE Std. 1588™ signals for test and measurement
- Real-time clock on I²C bus
- PCB
 - 6-layer routing (4-layer signals, 2-layer power and ground)

Figure 1 shows the P1025RDB block diagram.

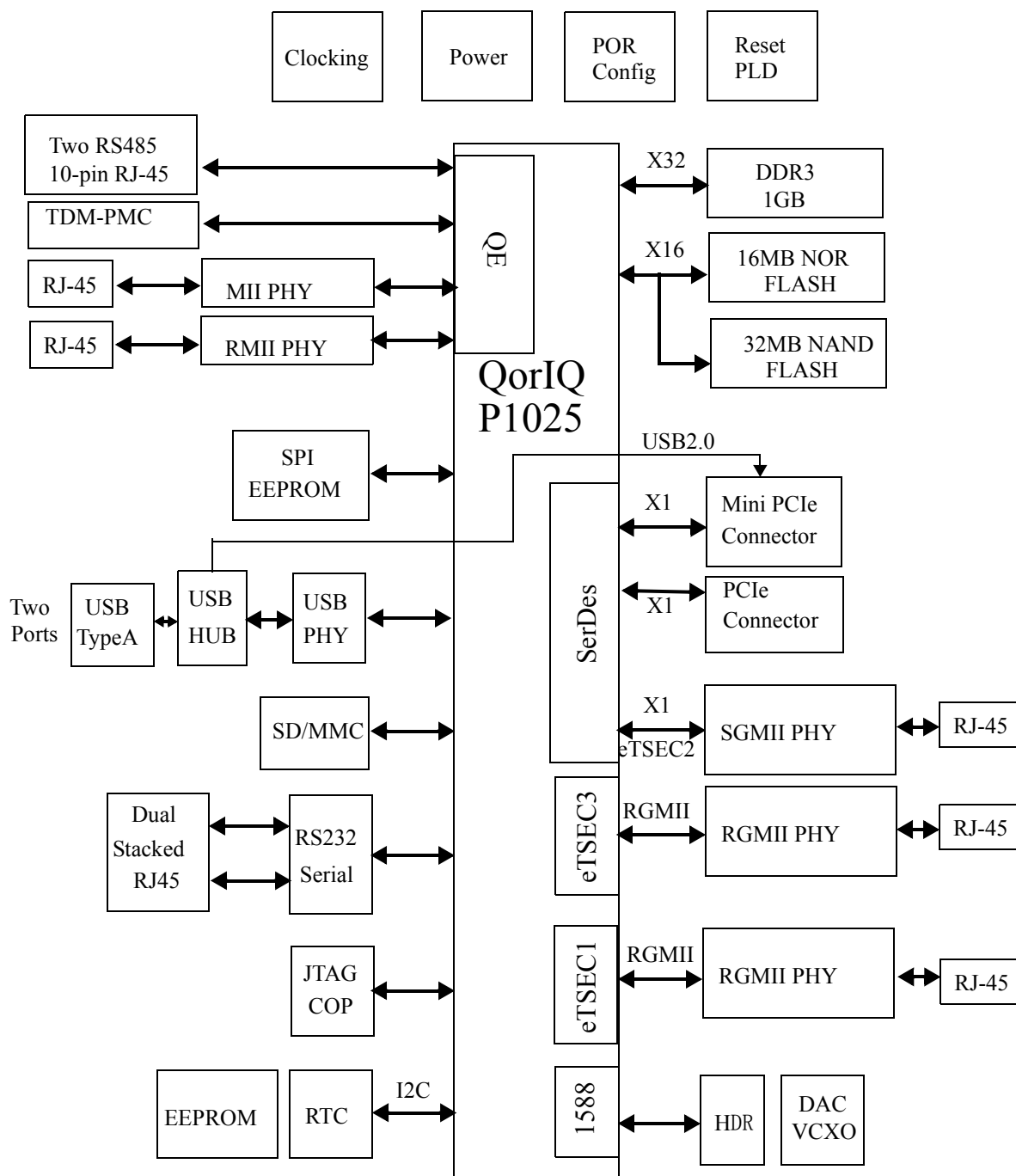


Figure 1. Block Diagram

2.2 Specifications

Table 2 lists the specifications of the P1025RDB.

Table 2. RDB Specifications

Characteristics	Specifications
Chassis Power requirements	Typical Maximum 40W 90~264VAC input open frame power supply
Communication processor	P1025E cores running at 533 MHz
Operating temperature	0° C to 70° C (room temperature)
Storage temperature	-25° C to 85° C
Relative humidity	5% to 90% (noncondensing)
PCB dimensions: Length Width Thickness	8860 mil 8270 mil 62 mil

2.3 Mechanical Data

Figure 2 shows the P1025RDB-PA dimensions. The board measures 225 mm × 210 mm (8860 mil × 8270 mil)

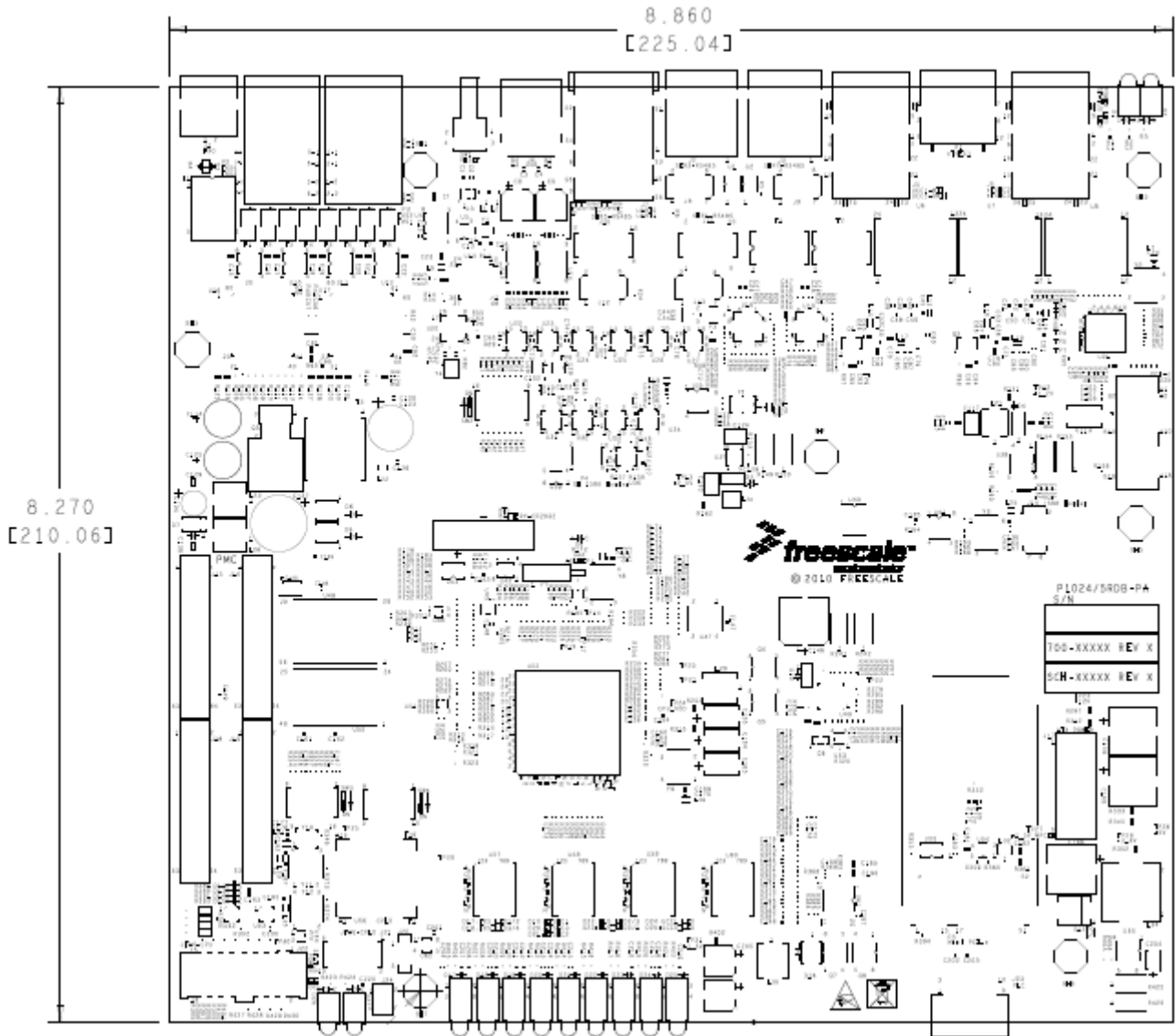


Figure 2. Dimensions of the RDB

3 Memory Interface

3.1 Description

The memory interface on the RDB is configured as DDR3 and is implemented as a single bank discrete chips(x8). ECC is not supported on the design. The memory size supported on the board is shown in [Table 3](#).

Table 3. Memory Size

P1025RDB-PA (32-bit)
1GB (4 chips * 2Gbit chips)/8bits

The PCB design is capable of running up to a clock rate of up 333 MHz (667 MHz data rate). The actual and final speed of the memory design is determined by the final supported DDR3 frequency of the processor.

The DDR3 interface uses the SSTL driver/receiver and 1.5 V power. A Vref 1.5 V/2 is needed for all SSTL receivers in the DDR3 interface. For details on DDR3 timing design and termination, refer to the Freescale application note entitled [Hardware and Layout Design Considerations for DDR Memory Interfaces \(AN2582\)](#)

Signal integrity test results show this design does not require terminating resistors (series resistor (R_S) and termination resistor (R_T)) for the discrete DDR3 devices used. DDR3 supports on-die termination; the DDR3 chips and P1025E are connected directly.

The interface is 1.5 V and is provided by an on-board voltage regulator. VREF, which is half the interface voltage, or 0.75 V, is supplied by the same voltage regulator.

Figure 3 shows the DDR3 SDRAM controller connection.

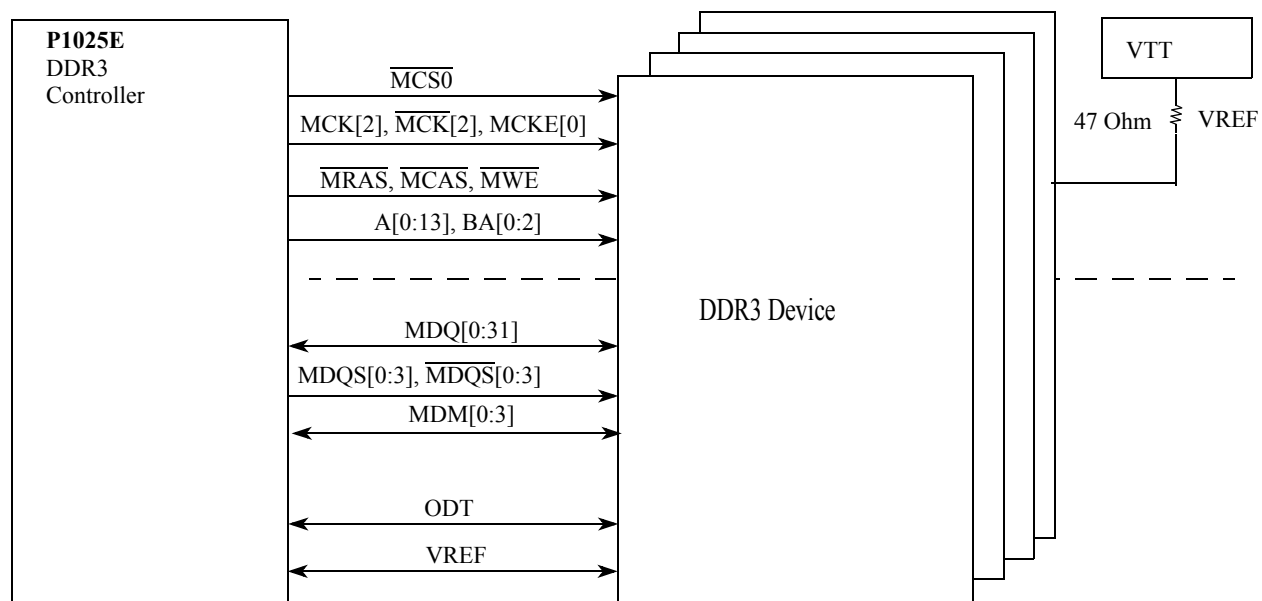


Figure 3. DDR3 SDRAM Connection

3.2 Termination

The DDR3 address, control, and command signals are terminated to the VTT rail via a 47 Ohm resistor.

4 SerDes Interfaces (PCIe/SGMII)

P1025E supports the SGMII and PCI Express high-speed I/O interface standards.

Table 4 details the SerDes connections.

Table 4. SerDes Connectivity

SerDes Lane	Mode	Connected to	Comment
Lane 0	PCI Express 1	Mini-PCIe slot	Used for WLAN type cards
Lane 1	PCI Express 2	Standard x1 PCIe slot	PCIe Slot is only intended for cards that are 10W or less

Table 4. SerDes Connectivity

SerDes Lane	Mode	Connected to	Comment
Lane 2	SGMII	Vitesse SGMII PHY	
Lane 3	not used	not used	

4.1 PCIe

On the RDB, lanes 0 and 1 are configured as two independent x1 PCI Express Interfaces. These interfaces are compliant with the PCI Express Base Specification Revision 1.0a. The physical layer of the PCI Express interface operates at a transmission rate of 2.5 Gbaud (data rate of 2.0 Gbps) per lane. The theoretical unidirectional peak bandwidth is 2 Gbps per lane. Receive and transmit ports operate independently, resulting in an aggregate theoretical bandwidth of 4 Gps per lane.

4.2 SGMII

Lane 2 is used in the serial gigabit media independent interface (SGMII). SGMII is a high-speed interface linking the Ethernet controller with an Ethernet PHY. SGMII uses differential signalling for electrical robustness. It requires only four signals: receive data and its inverse, and send data and its inverse.

Lane 3 of the SerDes Interface is not used on the card.

4.3 SerDes Clocking

The clocking for the SerDes interface is 100MHz provided by the PI6C557-05 clock chip.

5 Enhanced Local Bus Controller (eLBC) Interface

The eLBC port connects to a wide variety of external memories, DSPs, and ASICs.

Three state-machines, the GPCM, UPM, and FCM, share the same external pins and can be programmed separately to access different types of devices.

- GPCM, or general-purpose chip select machine, controls access to asynchronous devices using a simple handshake protocol.
- UPM, or user-programmable machine, can be programmed to interface with synchronous devices or custom ASIC interfaces.
- FCM, or NAND Flash control machine, further extends interface options.

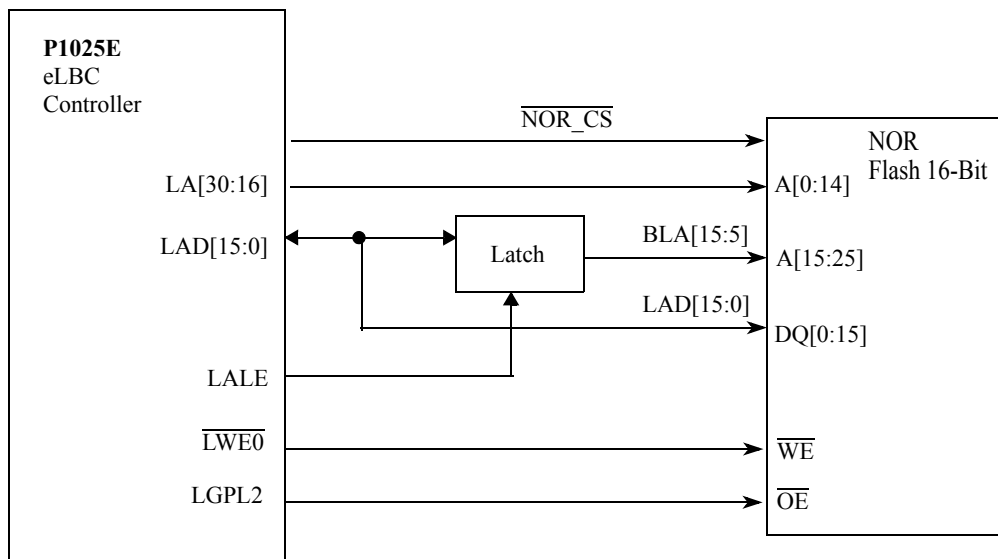
Every chip select signal can be configured so that the associated chip interface is controlled by the GPCM, UPM, or FCM state-machine. All state-machines can reside in the same system.

To interface with the standard memory device, an address latch is needed on the upper address bits since they are multiplexed with the data bus. The LALE is used as the latching signal. The followings modules are connected to the local bus:

- 16 Mbyte NOR flash memory
- 32 Mbyte NAND flash memory
- PLD (Lattice LCMXO1200C)
- PMC Connectors

5.1 NOR Flash Memory

Through the general-purpose chip-select machine (GPCM), the P1025RDB provides 16Mbyte of flash memory. The flash memory used is configured in a 16-bit port size. Figure 4 shows the hardware connections for the flash memory.



*NOTE: $\overline{\text{NOR_CS}}$ can be either $\overline{\text{CS0}}$ or $\overline{\text{CS1}}$ depending on boot location. See switch settings.

Figure 4. NOR Flash Connection

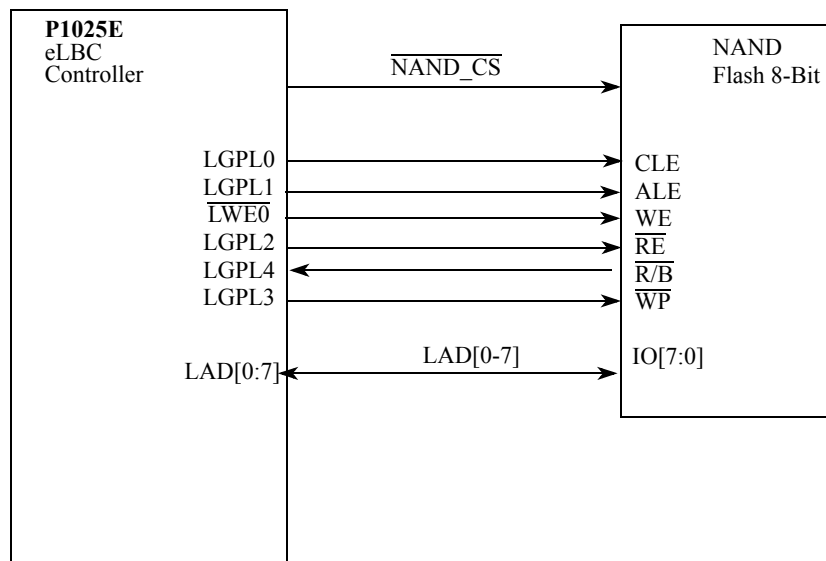
The NOR flash can be split into two logical halves by setting the FBANK_SEL signal. The FBANK_SEL signal is controlled by setting SW4[8]. Refer to Table 5 for details on changing the addresses using FBANK_SEL.

Table 5. Logical NOR Banks

Setting	NOR BANK used
SW4[8]=0	upper bank used for booting starting at address 0xEFF80000
SW4[8]=1	lower bank used for booting starting at address 0xEF780000

5.2 NAND Flash Memory

The P1025E has native support for NAND Flash memory through its NAND Flash control machine (FCM). The P1025RDB implements an 8-bit NAND Flash with 32 Mbyte in size. [Figure 5](#) shows the NAND Flash connection.



*NOTE: $\overline{\text{NAND_CS}}$ can be either $\overline{\text{CS0}}$ or $\overline{\text{CS1}}$ depending on boot location. See switch settings.

Figure 5. NAND Flash Connection

5.3 Lattice PLD

Lattice PLD LCMXO1200C is connected to the local bus of the processor. This gives the processor the ability to access the 8-bit registers in the PLD. For more details, refer to [P1025RDB-PA CPLD Specification-V0.3](#). [Figure 6](#) shows the connection between PLD and the P1025E.

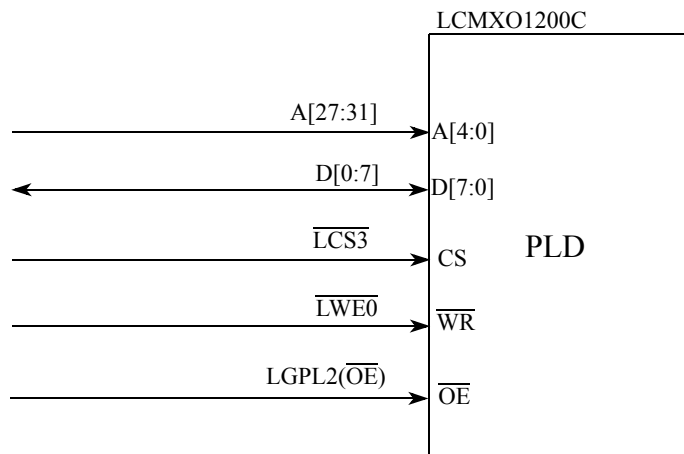


Figure 6. Local Bus Connection of PLD

Table 6 summarizes the eLBC connectivity.

Table 6. eLBC Connectivity

eLBC chip select	Manufacturer	Device	Comment
LCS0 or LCS1 Assignment dependent on which device is used for booting. Handled automatically by the POR PLD based on the switch setting.	Spansion	S29GL128P	NOR FLASH Memory 16 Mbyte (16bit)
LCS0 or LCS1 Assignment dependent on which device is used for booting. Handled automatically by the POR PLD based on the switch setting.	Samsung	K9F5608U0D-PCB0	NAND Flash 32 Mbytes (8bit)
LCS2	Freescale	PQ-MDS-T1	PMC Card
LCS3	Lattice	LCMXO1200C	PLD
LCS4-LCS7	not used	not used	

6 Ethernet

The RDB supports five Ethernet ports.

6.1 eTSEC1 10/100/1000 BaseT Interface

eTSEC1 is set to operate in RGMII and is directly connected to the Atheros RGMII PHY (AR8021), as shown in Figure 7. This port can be used for WAN connectivity.

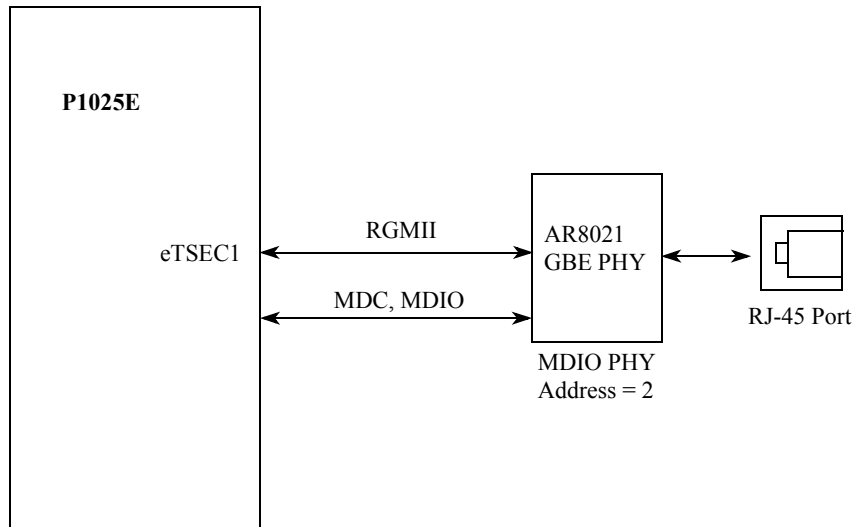


Figure 7. eTSEC1 Connection

6.2 eTSEC2 10/100/1000 BaseT Interface

eTSEC2 is set to operate in SGMII and is directly connected to the Vitesse SGMII PHY (VSC8221), as shown in Figure 8. This port can be used for WAN connectivity.

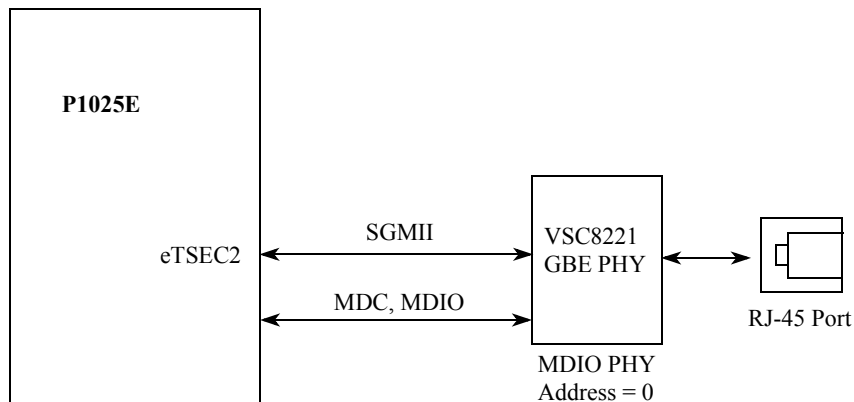


Figure 8. eTSEC2 Connection

6.3 eTSEC3 10/100/1000 BaseT Interface

eTSEC3 is set to operate in RGMII and is directly connected to the Atheros RGMII PHY (AR8021), as shown in Figure 9. This port can be used for WAN connectivity.

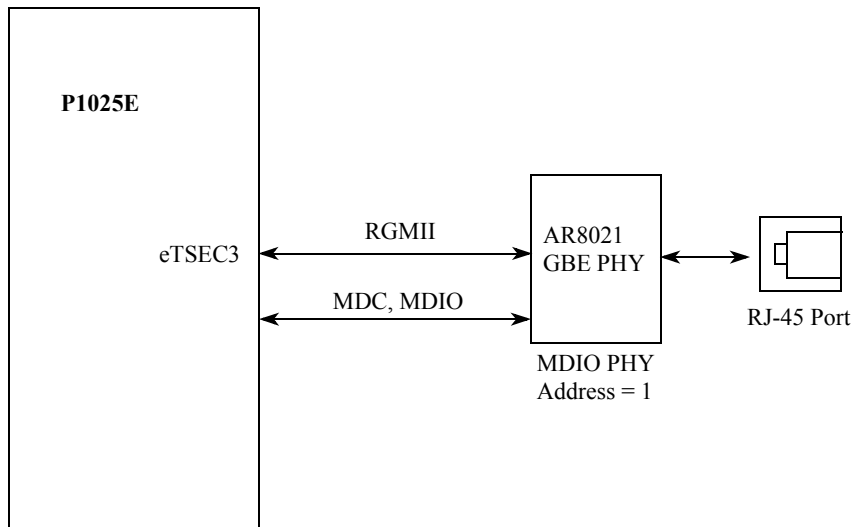


Figure 9. eTSEC3 Connection

6.4 UEC1 10/100 BaseT Interface

UEC1, the 10/100M Ethernet controller is from QE and is connected to the Micrel PHY (KSZ8041), as shown in Figure 10.

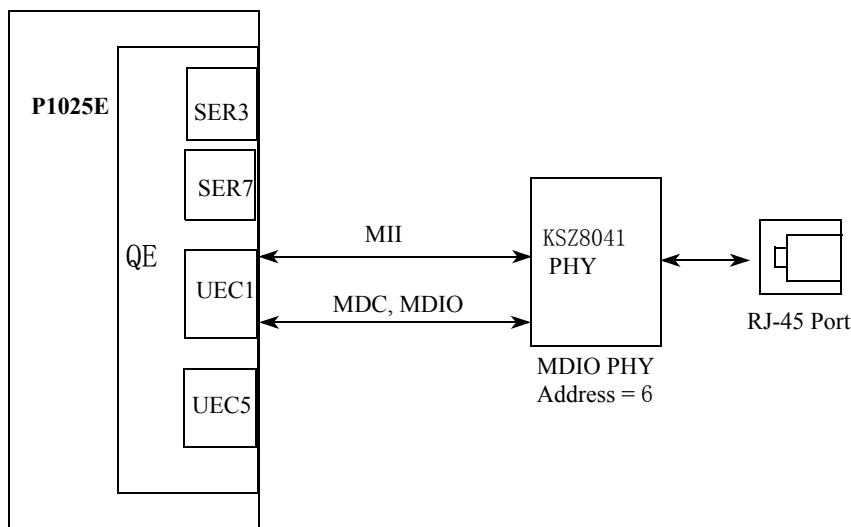


Figure 10. UEC1 Connection

6.5 UEC5 10/100 BaseT Interface

UEC5, the 10/100M Ethernet controller is from QE and is connected to the Micrel PHY (KSZ8041), as shown in Figure 11.

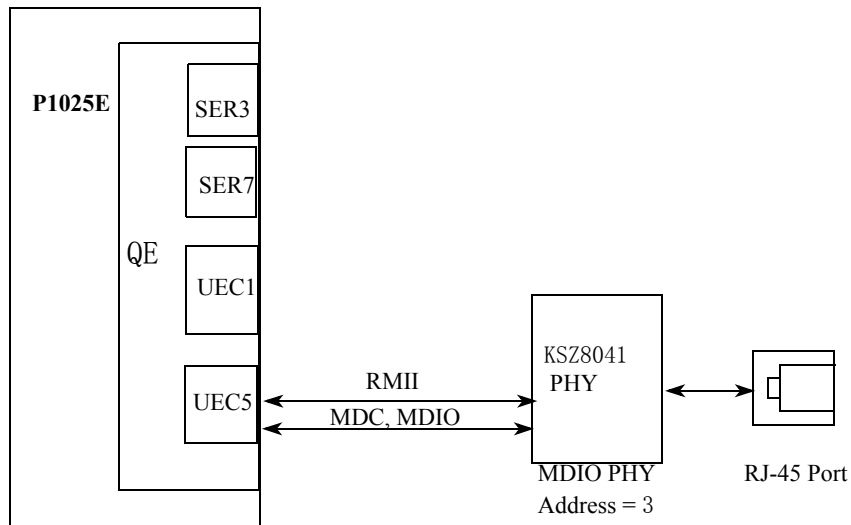


Figure 11. UEC5 Connection

6.6 Ethernet Management

Table 7 give details of the MDC and MDIO connections on the RDB.

Table 7. MDC/MDIO Connectivity

Device	PHY Address	Comment
eTSEC1 PHY	00010	AR8021
eTSEC2 PHY	00000	VSC8221
eTSEC3 PHY	00001	AR8021
UEC1 PHY	00110	KSZ8041
UEC5 PHY	00011	KSZ8041

6.7 Ethernet Ports

Figure 12 shows how the ethernet ports are connected on the backside of the RDB chassis.

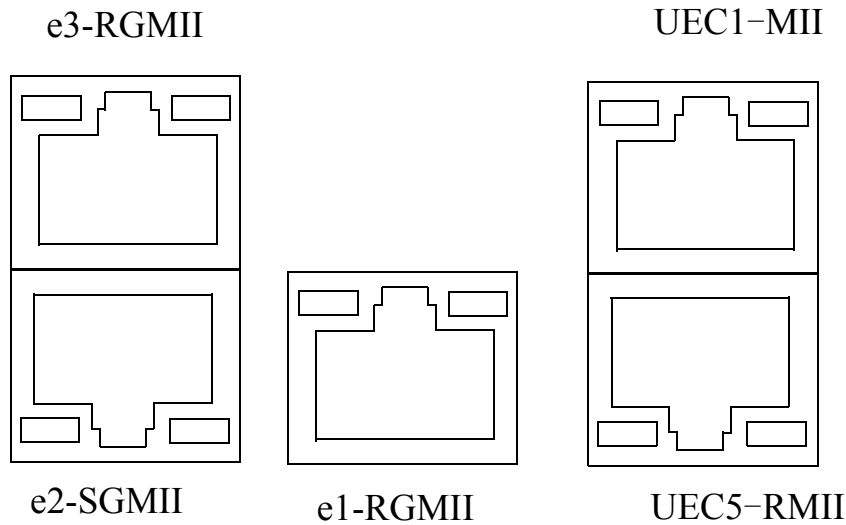


Figure 12. Ethernet Port Connectivity

7 eSPI

The eSPI is a full-duplex, synchronous, character-oriented channel that supports a four-wire interface (receive, transmit, clock, and slave select). The P1025E has the ability to boot from an SPI serial flash device. It also supports other peripheral devices conforming to the SPI standard. Some of the peripheral devices include real-time clocks and A/D converters devices.

On the RDB, a Spansion SPI flash memory is supported. Additionally, the SPI interface is also connected to 1588 test circuitry. [Table 8](#) lists the eSPI connections.

Table 8. eSPI Connectivity

eSPI Chip Select	Manufacturer	Part #	Comment
SPI_CS0_N	Spansion	S25FL128P0XN	16MB Spansion SPI Flash
SPI_CS1_N	N/A	N/A	Not Used
SPI_CS2_N	N/A	N/A	Not Used
SPI_CS3_N	Microchip	MCP4921	12-bit DAC

8 eSDHC Interface

The enhanced SD host controller (eSDHC) provides an interface between host system and SD/MMC cards. The secure digital (SD) card is specifically designed to meet the security, capacity, performance, and environmental requirements inherent in emerging audio and video consumer electronic devices. Booting from eSDHC interface is supported via the processor’s on-chip ROM.

On the RDB, a single connector is used for both SD and MMC memory cards as shown in [Figure 13](#).

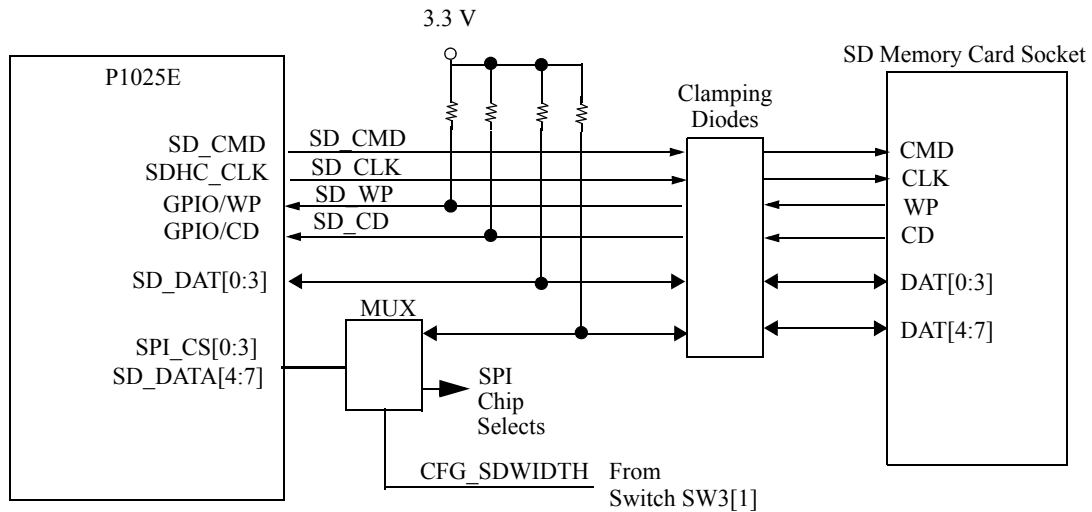


Figure 13. SD Memory Card Connection

The SPI chip selects are multiplexed with the higher data nibble of SDHC interface signals. The selection between the two is controlled by the `cfg_sdwidth` signal (switch3[1]). By default, `cfg_sdwidth = 0`, thereby allowing SPI and a 4-bit SD/MMC interface to co-exist on the board.

When `cfg_sdwidth = 1`, the on-board mux connects the upper data nibble to the SD/MMC connector. When doing this, the user must configure the processor in order to realize the increased bus width. Secondly, when used in this mode, SPI connectivity is not available.

[Table 9](#) lists the multiplexed signals.

Table 9. Multiplexed Signals

SPI Signal	Alternative Signal
SPI_CS0_B (IO)	SDHC_DAT4
SPI_CS1_B (IO)	SDHC_DAT5

Table 9. Multiplexed Signals

SPI Signal	Alternative Signal
SPI_CS2_B (IO)	SDHC_DAT6
SPI_CS3_B (IO)	SDHC_DAT7

9 GPIO

Table 10 lists the GPIO pin usage on the RDB platform.

Table 10. GPIO Pin Usage

GPIO	Input / Output	Signal Name	Comment
GPIO07	input	LOAD_DEFAULT_N	Default configuration load request via pushing down Reset Switch SW1 for more than 6 seconds
GPIO11	output	WDI	Periodic signal for Watchdog MAX6370 (U65) input

10 I²C

The P1025E device has two I²C controllers. On the RDB, the I2C buses are connected as shown in [Figure 14](#). The M24256 serial EEPROM can be used to store configuration registers' values and/or user program if the P1025E boot sequencer is enabled. For details about the boot sequencer mode, refer to the [P1025E reference manual](#). By default, the boot sequencer is not used and the boot code and initialization for the board is loaded from the local bus flash memory.

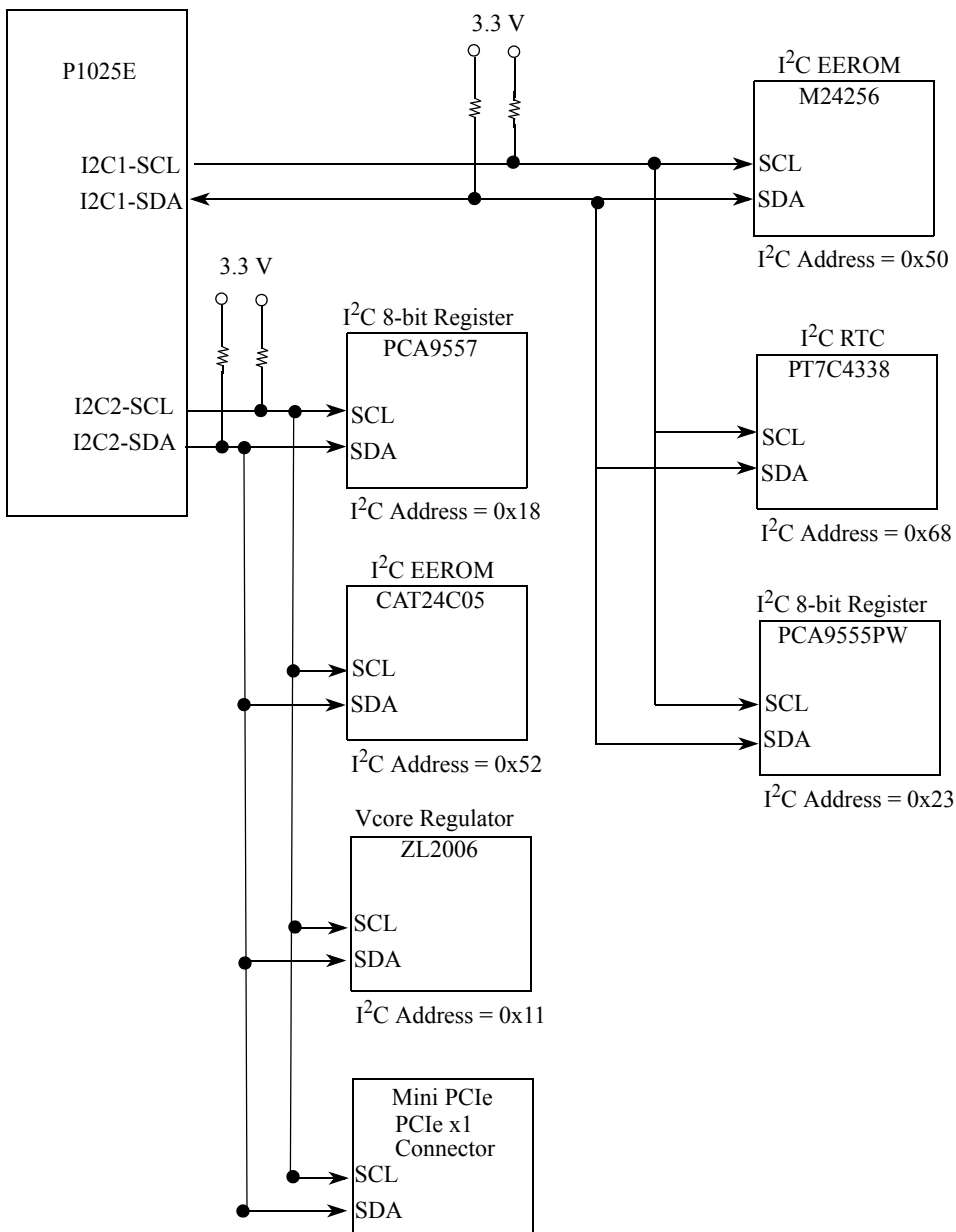


Figure 14. I²C Connection

Table 11. I2C Bus Connections

I2C Bus	I2C Address	Manufacturer	Device	Comment
I2C1	50H	ST Microelectronics	M24256	Boot sequencer eeprom 2 56Kbits
I2C1	68H	Pericom	PT7C4338	Real time clock
I2C2	11H	Zilker	ZL2006	Vcore Regulator
I2C2	18H	NXP	PCA9557	8-bit I2C register
I2C2	52H	ON-SEMICONDUCTOR	CAT24C05	SPD EEPROM 4Kbits
I2C2			Mini PCIe PCIe x1 Connector	
I2C2	23H	NXP	PCA9555PW	QE switch Configure

11 USB Interface

The USB interface is configured to operate as a standalone host. To complete the USB interface, an external PHY is employed and connected to the processor's ULPI signals. The SMSC USB3300 PHY is used on the RDB. Four downstream ports, and one upstream port USB Hub Genesys Logic GL850A is connected to the USB PHY to expand the USB ports.

The board features:

- High-speed (480 Mbps), full-speed (12 Mbps) and low-speed (1.5 Mbps) operation
- Host mode
- Dual stacked Type A connection
- One port connected to Mini PCIe connector

Figure 15 illustrates how the USB connectivity is implemented on the RDB.

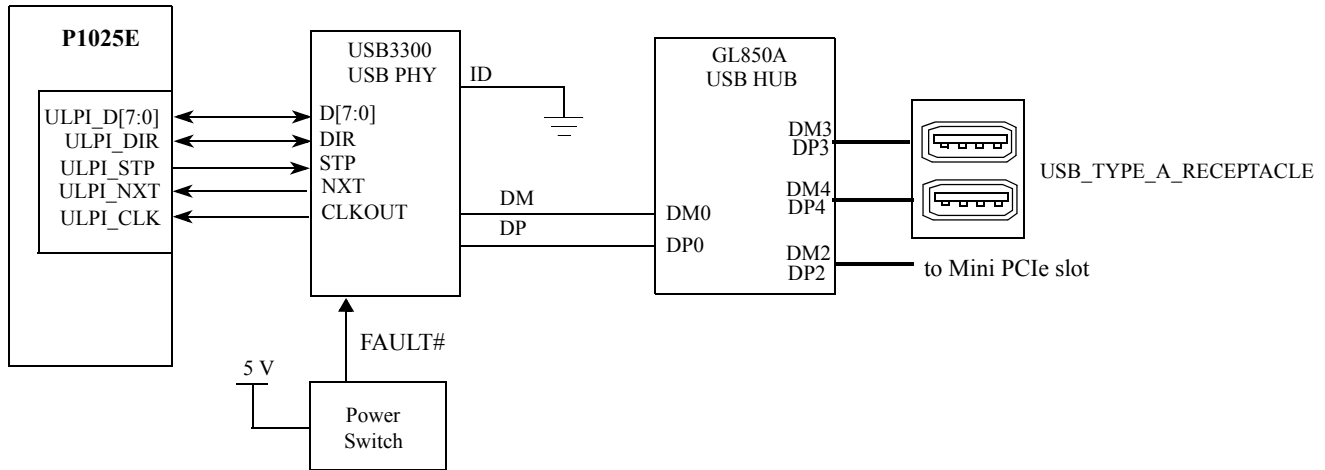


Figure 15. USB Interface

12 Dual RS-232 Ports

The P1025E device has two UART controllers. The RS-232 interface provides an RS-232 standard interconnection between the card and an external host. The serial connection is typically configured to run at 115.2 Kbps.

Each UART supports:

- Full-duplex operation.
- Software-programmable baud generators:
 - Divide the input clock by 1 to (216 – 1)
 - Generate a 16x clock for the transmitter and receiver engines
- Clear-to-send (CTS) and ready-to-send (RTS) modem control functions.
- Software-selectable serial interface data format that includes:
 - Data length
 - Parity
 - 1/1.5/2 STOP bit
 - Baud rate
- Overrun, parity, and framing error detection.

The UART ports are routed to dual stacked RJ45 connectors J7 as shown in Figure 16. UART0 is used as default port.

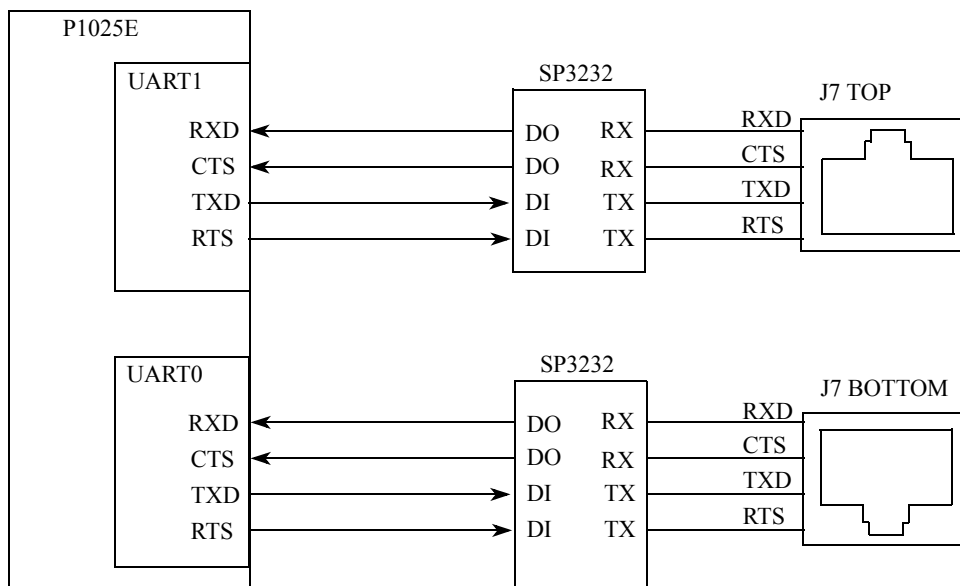


Figure 16. RS-232 Debug Ports Connection

Table 12 lists the connectivity for the UART RJ45 to DB9 female cable connections.

Table 12. UART Connections

RJ45 Pin#	RS-232 Signal	DB9 Female Pin#
1	RTS	8
2	NC	
3	TXD	2
4	GND	
5	GND	5
6	RXD	3
7	NC	
8	CTS	7

13 Lattice PLD

The Lattice PLD (U56) is used for power up sequence control, system reset, POR configuration, multiplexed function select and LEDs control. For details, refer to [P1025RDB-PA CPLD Specification-V0.3](#).

14 POR Configuration

14.1 POR Configuration PLD

The POR configuration PLD drives the appropriate configuration signals to the processor based on the selected configuration switch setting. When hard reset (HRESET) is asserted, the POR config PLD begins to drive the POR config signals to the processor. The config signals remain asserted until the POR config signals have been properly latched by the processor. The POR configuration PLD does not drive all POR configuration pins, but just those that are needed for frequency selection and boot location.

14.2 POR Configuration Resistors

The POR settings that are not set by the POR configuration PLD are controlled via on-board resistors. For a list of POR configuration resistors, refer to page 16 of the schematic.

15 JTAG/COP

The JTAG connection is provided by a direct connection to the appropriate header connector.

15.1 COP/JTAG Port

The common on-chip processor (COP) is part of the P1025E's JTAG module and is implemented as a set of additional instructions and logic. This port can connect to a dedicated emulator for extensive system debugging. Several third-party emulators in the market can connect to the host computer through the Ethernet port, USB port, parallel port, RS-232, and so on. A typical setup using a USB port emulator is shown in [Figure 17](#).

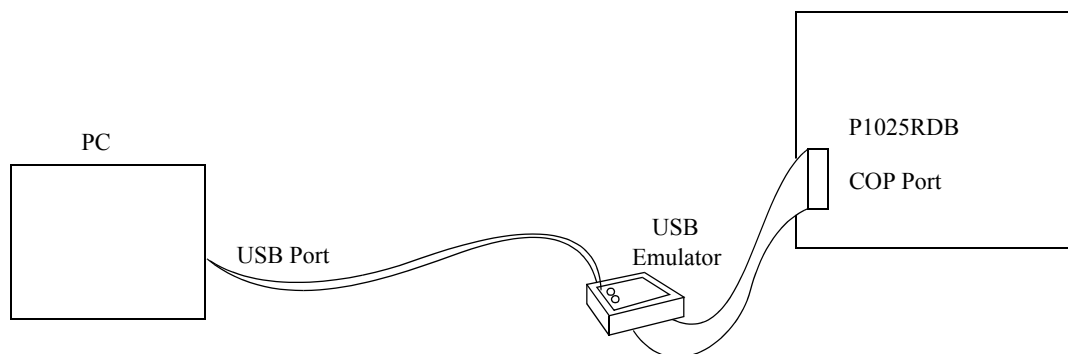


Figure 17. Connecting P1025RDB-PA to a USB Emulator

The 16-pin generic header connector carries the COP/JTAG signals and the additional signals for system debugging. The pinout of this connector is shown in [Figure 18](#).

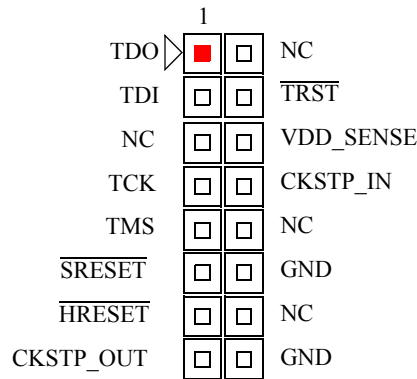


Figure 18. RDB COP Connector

[Table 13](#) lists the connections made from the RDB COP Connector

Table 13. Connectivity from the COP Connector

Pin Number		
Pin #	Signal Name	Connection
1	TDO	Connected directly between the processor and JTAG/COP connector.
2	NC	Not connected
3	TDI	Connected directly between the processor and JTAG/COP connector.
4	TRST	Routed to the RESET PLD. TRST to the processor is generated from the PLD.
5	NC	Not connected
6	VDD_SENSE	Pulled to 3.3V via a 10 Ohm resistor
7	TCK	Connected directly between the processor and JTAG/COP connector.
8	CKSTP_IN	Connected directly between the processor and JTAG/COP connector.
9	TMS	Connected directly between the processor and JTAG/COP connector.
10	NC	Not connected
11	SRESET	Routed to the RESET PLD. SRESET to the processor is generated from the PLD.
12	GND	Connected to ground
13	HRESET	Routed to the RESET PLD. HRESET to the processor is generated from the PLD.

Table 13. Connectivity from the COP Connector

Pin Number		
14	KEY	Not connected
15	CKSTP_OUT	Connected directly between the processor and JT AG/COP connector.
16	GND	Connected to ground

16 Interrupts

Figure 19 shows the external interrupts to the P1025E.

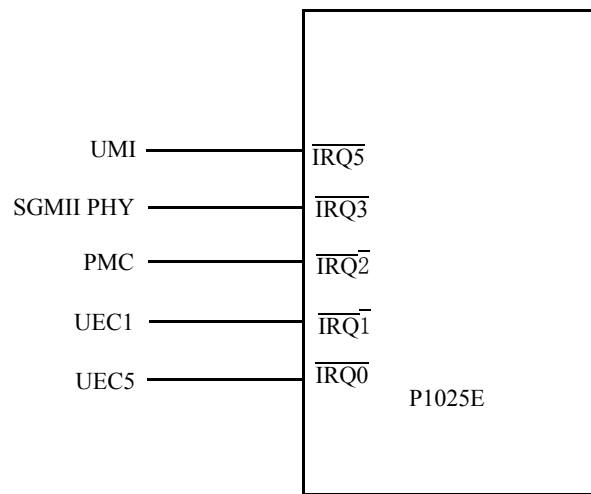


Figure 19. P1025E Interrupts

Table 14 lists how the interrupts are connected on the RDB platform.

Table 14. Interrupts

Name	Connection	Note
IRQ0	UEC5 PHY KSZ8041	On-board Pull-up
IRQ1	UEC1 PHY KSZ8041	On-board Pull-up
IRQ2	PMC Card	On-board Pull-up
IRQ3	SGMII PHY VSC8221	On-board Pull-up
IRQ4	Not used	On-board Pull-up
IRQ5	UMI(PLC)	On-board Pull-up

Table 14. Interrupts (continued)

Name	Connection	Note
IRQ6	not used	On-board Pull-up
IRQ_OUT	not used	On-board Pull-up

17 DMA

The DMA function itself is not utilized on the RDB platform. Unused input pins are pulled high. Since certain DMA pins have POR functionality, these pins are connected on the platform.

18 RS485

There are two full duplex RS485 interface with 10-pin RJ45 connectors. Within the QUICC Engine, UCC3 and UCC7 two universal controllers are configured as UART controllers. Besides, two transceivers on the board are used to convert UART signal to RS485 signal. Figure 20 shows how the RS485 is connected to the QE interface of P1025E device.

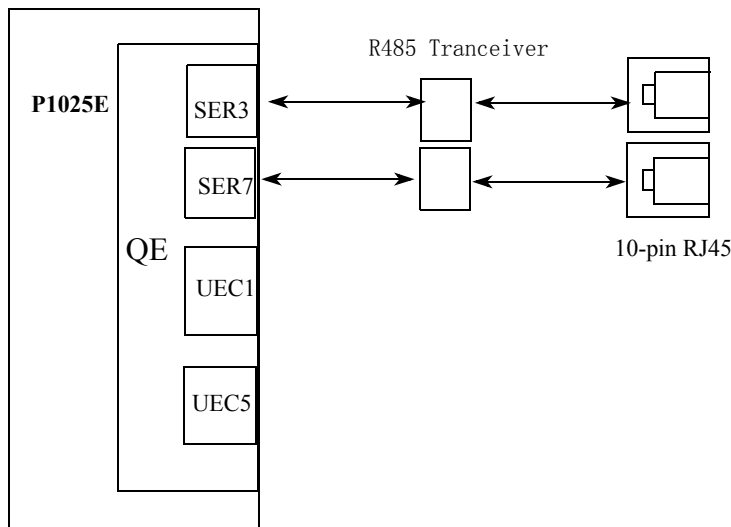


Figure 20. RS485 Connection

19 PMC

The RDB provides QUICC Engine evaluation through 4x TDM ports. A set of PMC connectors (PMC0) have been added on the RDB boards themselves. TDM signals are terminated to PMC0. The T1/E1 card on PMC0 tests the TDMs of the QUICC Engine block. Table 15 lists QE TDM function pin map.

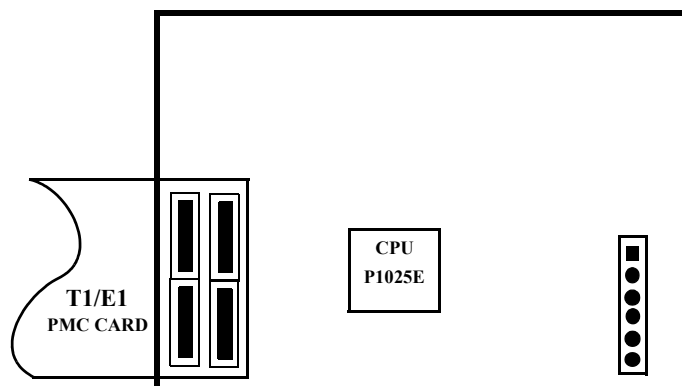
Table 15. QUICC Engine Block Functions

Functional Pin	PQ Pin	4TDM Sigansls
LDP0	CE_PA11	TDMB_RXD1
LDP1	CE_PA12	TDMB_RXD2
LA28	CE_PA13	TDMB_RXD3
LGPL5	CE_PA14	TDMB_TXD1
GPIO11	CE_PA15	TDMB_TXD2
LCLK1	CE_PA16	TDMB_TXD3
LA24	CE_PA18	TDMD_TXD0
LA25	CE_PA19	TDMD_RXD0
LA26	CE_PA20	TDMD_TSYNC
LA27	CE_PA21	TDMD_RSYNC
LCS_B7	CE_PA27	TDMB_TXCLK
CE_PB20	CE_PB20	TDMB_RXD[0]
LA31	CE_PA30	TDMB_TSYNC
GPIO6	CE_PA31	TDMB_RSYNC
GPIO5	CE_PB0	TDMB_TXD[0]
GPIO7	CE_PB1	TDMB_RXCLK
GPIO0	CE_PB4	TDMC_TXD[0]
GPIO4	CE_PB5	TDMC_RXD[0]
GPIO1	CE_PB6	TDMC_TSYNC
GPIO3	CE_PB7	TDMC_RSYNC
LWE_B1	CE_PB9	TDMC_TXD1
IRQ6	CE_PB10	TDMC_RXCLK
GPIO2	CE_PB11	TDMC_TXCLK
GPIO8	CE_PB12	TDMA_RXCLK
GPIO9	CE_PB13	TDMA_TXCLK
UART_CTS1#	CE_PB14	TDMC_RXD3
UART_RTS1#	CE_PB15	TDMC_TXD2
UART_SIN1	CE_PB16	TDMC_TXD3
UART_SOUT1	CE_PB17	TDMC_RXD1
CE_PB18	CE_PB18	TDMC_RXD2
DMA2_DACK0#	CE_PB19	SPI1_MOSI
LBCTL	CE_PA29	SPI1_SEL#

Table 15. QUICC Engine Block Functions

Functional Pin	PQ Pin	4TDM Sigansls
IIC2_SDA	CE_PB21	SPI1_CLK
IIC2_SCL	CE_PB22	SPI1_MISO
MSRCID0	CE_PB23	TDMA_TXD[0]
MSRCID1	CE_PB24	TDMA_RXD[0]
MSRCID2	CE_PB25	TDMA_TSYNC
MSRCID3	CE_PB26	TDMA_RSYNC
GPIO14	CE_PB31	TDMD_TXCLK
GPIO15	CE_PC0	TDMD_RXCLK

The supported PMC card is Freescale PQ-MDS-T1. The supported SLIC module is Zarlink Le71HR8820G. [Figure 21](#) shows the connection when PMC card is inserted to P1025RDB. Refer to [P1025RDB-PA Quick Start Guide rev0.1](#) for details of the process to evaluate TDM function.


Figure 21. PMC Card inserted to P1025RDB-PA

20 Connectors, Headers, Push Buttons and LEDs

20.1 Headers

[Table 16](#) lists the various headers on the RDB platform.

Table 16. Headers

Reference Designators	Used for	Note
J21	Lattice Header	Used for programming the Lattice PLD devices.
J14	1588	
J22	COP/JTAG	

Table 16. Headers

Reference Designators	Used for	Note
J20	PLC/DAC	Jumper to select PLC or DAC of 1588
J8	SER3 RS485	Modem Line CD,CTS,RTS and CLK1
J9	SER7 RS485	Modem Line CD,CTS,RTS and CLK2
J10	SER5 RS485	TX and RX signal
J12	SER5 RS485	Modem Line CD,CTS,RTS and CLK4
J11	SER1 RS485	TX and RX signal
J13	SER1 RS485	Modem Line CD,CTS,RTS and CLK3
J26	Reset remote control	

20.2 Connectors

Table 17 lists all the connectors on the RDB platform.

Table 17. Connectors

Reference Designators	Used for	Note
J17	Open Frame Power	
J25	SD/MMC Card	
U35	PCIe x1 cards	Intended use is for PCIe cards that are 10W are less.
P5	Mini-PCIe cards	
J6	Ethernet Port	Bot port-eTSEC2 (SGMII); VSC8221 Top port-eTSEC3(RGMII); AR8021
P1	Ethernet Port	eTSEC1 (RGMII); AR8021
J5	Ethernet Port	Top -UEC1 Bot - UEC5
J2	RS485 Ports	SER3
J3	RS485 Ports	SER7
J4	Dual Type A USB	
J7	UART	Top-UART1 Bot -UART0
BT1	Battery Holder	CR-2032
J23	UMI(PLC)	
J15/J16/J18/J19	PMC	

20.2.1 Battery Holder

The board contains an RTC that requires a battery in order to maintain the data inside the RTC. The battery holder (BT1) accommodates a CR-2032. [Figure 22](#) shows how to insert a battery.

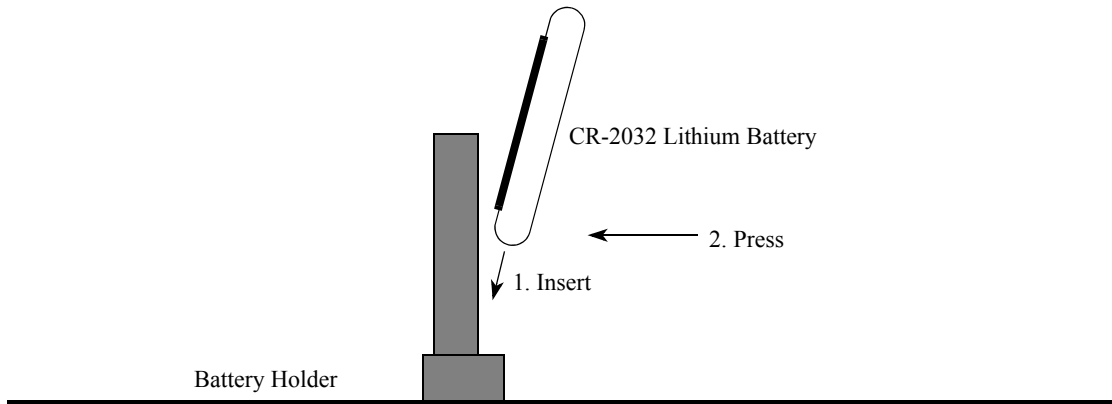


Figure 22. Installation of Battery

20.3 Push Buttons

[Table 18](#) details how the push buttons are used on the RDB platform.

Table 18. Push Buttons

Reference Designators	Used for
SW1	Reset

20.4 LEDs

[Table 19](#) details all the LEDs on the RDB chassis.

Table 19. LEDs

LEDs	Used for	Controlled by
D26	Power on	+3.3V rail
D27	Status	Lattice PLD (U44)
D19	TOP: Link BOT: Activity	eTSEC1 RGMII PHY AR8021

LEDs	Used for	Controlled by
D20	TOP: Link BOT: Activity	eTSEC3 RGMII PHY AR8021
D21	TOP: Link BOT: Activity	eTSEC2 SGMII PHY VSC8221
D22	ELB LED0	CPLD
D23	ELB LED1	CPLD
D24	TOP: Link BOT: Activity	UEC1 PHY KSZ8041
D25	TOP: Link BOT: Activity	UEC5 PHY KSZ8041

Refer to [P1025RDB-PA CPLD Specification-V0.3](#) for details on controlling the LEDs by Lattice PLD. [Figure 23](#) shows LEDs on the P1025RDB front side chassis.

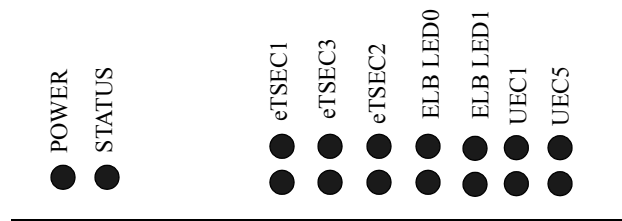


Figure 23. LEDs on Chassis

21 Power Related

21.1 Open Frame Power Supply

Open Frame power supply PD45 supplies +12V and +5V for the RDB board. The rated power is 40W.

21.2 CPU_VDD

The CPU core voltage CPU_VDD rail is sourced from an Intersil switching regulator. The device used on the RDB is the ZL2006. CPU_VDD=1.0V

21.3 AVDD Signals

All AVDD pins are sourced by the CPU_VDD rail through the recommended filter circuit.

21.4 DDR

The memory interface power rails (VTT, GVDD, and VREF) are sourced by a TI switching regulator. The part used is the TPS51116 device. For DDR3, VTT=0.75V, GVDD=1.5V, and VREF = 0.75V.

21.5 SerDes

The SerDes rails (SVDD, XVDD) are sourced from the on-board CPU_VDD core voltage rail.

21.6 USB, SPI, eSDHC (CVDD)

Each of these rails are sourced from 3.3V rail, which is a dedicated power plane on the board. The 3.3V rail is from an MPS switching regulator MP2380.

21.7 Local Bus (BVDD)

This rail is sourced from 3.3V, which is a dedicated power plane on the board.

21.8 DUARTs, System Control, I2C, JTAG (OVDD)

This rail is sourced from 3.3V, which is a dedicated power plane on the board.

21.9 eTSECs (LVDD)

The LVDD rail is used for the TSEC I/Os and is configured for 2.5V operation. The rail is sourced from MPS switching regulator, part number MP2119DQ.

21.10 Mini-PCIE (+1.5V)

The +1.5V rail is used by the mini-PCIE slot and is sourced by an MPS switching regulator. The part used is the MP2105DJ device.

21.11 PCIe x1 slot (+3.3V and +12V)

The PCIe x1 slot +12V rail is directly derived from power supply. The 3.3V is sourced from MPS switching regulator MP2380.

21.12 Vitesse Devices (+1.2V)

The +1.2V rail used by the Vitesse devices is sourced by an MPS Switching Regulator. The part used is the MP2365 device.

21.13 Micrel and Atheros Device(+3.3V)

The +3.3V rail used by the Micrel devices is sourced from MPS switching regulator MP2380.

21.14 Voltage Selection

The P1025E device supports multiple supply voltages on its I/O supplies. [Table 20](#) shows the configuration of the voltage selection pins on the RDB platform.

Table 20. I/O Supply Voltage Selection

Signal Name	Connection	Comment
LVDD_SEL	Pulled high. LVDD = 2.5V	eTSEC1, 2, 3, Ethernet management, 1588
BVDD_VSEL[0:1]	Pulled high. BVDD = 3.3V	Local Bus, GPIO[8:15]
CVDD_VSEL[0:1]	Pulled high. CVDD = 3.3V	USB, SD/MMC, SPI

22 1588

The 1588 signals are routed to a 1588 header on the board (J14). The 1588 clock input into the processor can be controlled over the SPI interface through a 12-bit digital-to-analog converter (U41). The output of the DAC feeds directly into a precision VCXO which in turn is used to drive the 1588 clock into the processor. The DAC and VCXO combination allows the 1588 clock to be varied as needed for testing.

23 Clocking

The input system clock for the processor is a 66.66 MHz clock source. The DDR clock input is also driven by a 66.66 MHz clock source. All PCIe ports receive a dedicated 100 MHz clock. All Gigabit PHYs receive a dedicated 25 MHz oscillator clock. UEC5 CLK for MAC and PHY is driven by a clock buffer which uses a 50MHz oscillator as clock source. UEC1 PHY receives a dedicated 25 MHz oscillator clock.

24 Reset

All resets for the board are handled by the PLD (U56). Power-on reset is initiated by pressing the power switch if the board is in a chassis. Warm reset is initiated by pressing SW1 on the board. Software is also capable of initiating a warm reset by asserting the HRESET_REQ line from the processor.

25 Switch Settings

The RDB has user selectable switches for evaluating different frequency and boot options for the P1025E device. [Table 20](#) describes the available options.

25.1 P1025RDB Configuration (Switch Method)

NOTE

All frequencies listed below assume that the input SYSCLK is set to 66.66 MHz for P1025RDB.

Table 21. P1025E Dure Core Configuration Options

Switch Settings SW4[1:6]	Switch Settings SW3[2:3]	Core0 Freq (MHz)	Core1 Freq (MHz)	Platform (MHz)	DDR Freq (MHz)	Boot Location	Boot Hold-off
110000	10	533	533	267	667	NOR	Core0 boot; Core1 hold-off
110001	10	533	533	267	667	SD/MMC	Core0 boot; Core1 hold-off
110010	10	533	533	267	667	SPI	Core0 boot; Core1 hold-off
110011	10	533	533	267	667	NAND	Core0 boot; Core1 hold-off
110100	10	400	400	267	667	NOR	Core0 boot; Core1 hold-off
110101	10	400	400	267	667	SD/MMC	Core0 boot; Core1 hold-off
110110	10	400	400	267	667	SPI	Core0 boot; Core1 hold-off
110111	10	400	400	267	667	NAND	Core0 boot; Core1 hold-off

Table 22. P1025E Single Core Config Options

Switch Settings SW4[1:6]	Switch Settings SW3[2:3]	Core0 Freq (MHz)	Core1 Freq (MHz)	Platform (MHz)	DDR Freq (MHz)	Boot Location	Boot Hold-off
110000	01	533	N/A	267	667	NOR	Core0 boot
110001	01	533	N/A	267	667	SD/MMC	Core0 boot
110010	01	533	N/A	267	667	SPI	Core0 boot
110011	01	533	N/A	267	667	NAND	Core0 boot
110100	01	400	N/A	267	667	NOR	Core0 boot
110101	01	400	N/A	267	667	SD/MMC	Core0 boot
110110	01	400	N/A	267	667	SPI	Core0 boot
110111	01	400	N/A	267	667	NAND	Core0 boot
100000	01	667	N/A	333	667	NOR	Core0 boot
100001	01	667	N/A	333	667	SD/MMC	Core0 boot
100010	01	667	N/A	333	667	SPI	Core0 boot
100011	01	667	N/A	333	667	NAND	Core0 boot

Note:667MHz core frequency can only be supported at P1015/P1016 platform.SW3[2:3]=10,dual core;SW3[2:3]=01,single core

25.2 Other configuration options

Table 23 describes the other configuration options available on the board.

Table 23. Other Config Options

Switch	Signal Name	Signal Meaning	Setting
SW4[7]	LGPL5 (cfg_boot_seq[1])	Selects whether the boot sequencer is enabled during boot-up.	OFF: boot sequencer enabled and configuration information loaded from I2C ROM. A valid ROM must be present. If not card will hang. ON: boot sequencer disabled
SW4[8]	FBANK_SELECT	Selects which NOR flash bank is selected.	OFF: upper 4 sectors used for booting ON: middle 4 sectors used for booting
SW3[1]	CFG_SDWIDTH	Configures the width of the SD/MMC bus, 4-bit or 8-bit	OFF: then width = 4bits, SPI interface active ON: then width = 8bits Software can read the status of this bit by reading the I2C 8-bit register.
SW3[2]	TEST_SEL	Personality Selection	OFF: Single e500 Core Device (P1016) ON: Dual e500 Core Device (P1025)
SW3[3]	DMA1_DACK_N	Freescale use only	Set to OFF for P1025E Set to ON for P1016E
SW3[4]	LA19 (cfg_host_agt[2])	Controls the setting of the cfg_host_agt[2] pin	ON: cfg_host_agt[2] = 1 OFF: cfg_host_agt[2] = 0 Refer to Section 25.4, Configuring Host/Agent Mode
SW3[5]	USB1_STP	Freescale use only	Must be set to OFF for P1025E
SW3[6]	SWITCH7	Reserved	Default ON
SW3[7]	LA18 cfg_host_agt[1]	Controls the setting of the cfg_host_agt[1] pin	ON: cfg_host_agt[1] = 1 OFF: cfg_host_agt[1] = 0 Refer to Section 25.4, Configuring Host/Agent Mode
SW3[8]	LWE1_N (cfg_host_agt[0])	Controls the setting of the cfg_host_agt[0] pin	ON: cfg_host_agt[0] = 1 OFF: cfg_host_agt[0] = 0 Refer to Section 25.4, Configuring Host/Agent Mode

25.3 Factory Settings of board switches

Table 24 shows default settings of all the switches on SW4 and SW3.

Table 24. Default Settings of Board Switches

Switch	1	2	3	4	5	6	7	8
SW4	ON	ON	OFF	OFF	OFF	OFF	ON	ON
SW3	OFF	ON	OFF	ON	OFF	ON	ON	ON

25.4 Configuring Host/Agent Mode

Table 25 shows how the PCIe port can be configured in either Host or Agent mode.

Table 25. Host/Agent Selection

Device	Configuration	cfg_host_agt[0] controlled by SW3[8]	cfg_host_agt[1] controlled by SW3[7]	cfg_host_agt[2] controlled by SW3[4]
P1025E	P1025E acts as the host/root complex for all PCIe interface (default)	SW3[8] =ON cfg_host_agt[0] = 1	SW3[7] =ON cfg_host_agt[1] = 1	SW3[4] =ON cfg_host_agt[2] = 1
P1025E	P1025E acts as an host on PCIe 1 and acts as an agent on PCIe 2	SW3[8] =OFF cfg_host_agt[0] = 0	SW3[7] =ON cfg_host_agt[1] = 1	SW3[4] =OFF cfg_host_agt[2] = 0
P1025E	P1025E acts as an agent on PCIe 1 and acts as an host on PCIe 2	SW3[8] =OFF cfg_host_agt[0] = 0	SW3[7] =OFF cfg_host_agt[1] = 0	SW3[4] =ON cfg_host_agt[2] = 1
P1025E	P1025E acts as an agent on all its PCI Express interfaces.	SW3[8] =OFF cfg_host_agt[0] = 0	SW3[7] =OFF cfg_host_agt[1] = 0	SW3[4] =OFF cfg_host_agt[2] = 0

25.5 Reading and Writing Certain Board Switches

An 8-bit I2C register allows software to override certain switches remotely without having to change the physical switch. In addition, the CFG_SDWIDTH status can also be read via the I2C register. The I2C register is implemented by Philips PCA9557 device. The register definition is shown in [Table 26](#). The mapping between the I2C register bits and the switches are shown [Table 27](#). The I2C switch is located on I2C2 and is accessible at address 18H.

After being set, software must issue a reset command (asserting HRESET_REQ_B) for the new switch settings to take effect. Once the I2C registers are written and enabled, they override the board switches until either the I2C bits are disabled or a power cycle occurs.

Table 26. PCA9557 Register Definition

Name	Type	Function
Register 0	Read	Input port register
Register1	Read/Write	Output port register

Name	Type	Function
Register 2	Read/Write	Input pins polarity inversion register =1, the corresponding port pin's polarity is inverted =0, the corresponding port pin's original polarity is retained Note that default value of this register is: Bit [7:4] = 1, polarity inverted Bit [3:0] = 0, polarity not inverted
Register 3	Read/Write	Configuration register =1, the corresponding port pin is enabled as an input =0, the corresponding port pin is enabled as an output Note that default value of this register is FF

Table 27. Mapping between I2C register and POR switches

I2C Register Bit	Comment
I07	overrides SW4[1], and thereby controls Switch1
I06	overrides SW4[2], and thereby controls Switch2
I05	overrides SW4[3], and thereby controls Switch3
I04	overrides SW4[4], and thereby controls Switch4
I03	overrides SW4[5], and thereby controls Switch5
I02	overrides SW4[6], and thereby controls Switch6
I01	overrides SW4[8]; and thereby controls FBANK_SELECT
I00	“read-only” of CFG_SDWIDTH switch SW3[1]

25.5.1 Uboot steps for overriding on-board switches to change frequency

1. First change to the correct I2C bus
 - => i2c dev 1
 - Setting bus to 1
2. A read of the input register will return the current state of the on-board switches
 - => i2c md 18 0
 - 0000: 32 32 32 32 32 32 32 32 32 32 32 32 32 32 32
 - Set you desired values for switches.
 - => i2c mw 18 1 10
3. Next, set appropriate pins as outputs.
 - => i2c mw 18 3 ef

Switch Settings

4. A read will return the current over-written value that will be used for all subsequent resets.
 - => i2c md 18 0
 - 0000: 22 22 22 22 22 22 22 22 22 22 22 22 22 22 22 22
 - This value will be used until either the power is turned off, until the pins from the I2C device are tri-stated

25.5.2 Example log file showing change of frequencies via software

U-Boot 2010.12-00063-g8669298-dirty (Jul 09 2011 - 14:37:56)

CPU0: P1025E, Version: 1.1, (0x80ec0311)

Core: E500, Version: 5.1, (0x80212051)

Clock Configuration:

CPU0:533.333 MHz, CPU1:533.333 MHz,

CCB:266.667 MHz,

DDR:333.333 MHz (666.667 MT/s data rate) (Asynchronous), LBC:16.667 MHz

QE:266.667 MHz

L1: D-cache 32 kB enabled

I-cache 32 kB enabled

Board: P1025RDB CPLD: V2.6 PCBA: V2.0

rom_loc: nor lower bank

SD/MMC : 4-bit Mode

eSPI : Enabled

I2C: ready

SPI: ready

DRAM: Detected UDIMM(s)

DDR: 1 GiB (DDR3, 32-bit, CL=5, ECC off)

FLASH: 16 MiB

L2: 256 KB enabled

NAND: 32 MiB

MMC: FSL_ESDHC: 0

Firmware 'Microcode version 0.0.1 for P1021 r1.0' for 1021 V1.0

QE: uploading microcode 'Microcode for P1021 r1.0' version 0.0.1

PCIe1: Root Complex of mini PCIe SLOT, no link, regs @ 0xffe0a000

PCIe1: Bus 00 - 00

PCIe2: Root Complex of PCIe SLOT, no link, regs @ 0xffe09000

PCIe2: Bus 01 - 01

Video: No radeon video card found!

In: serial

Out: serial

Err: serial

Net: eTSEC2 is in sgmiI mode.

eTSEC1, eTSEC2, eTSEC3

Hit any key to stop autoboot: 0

=>

=> i2c dev 1

Setting bus to 1

=> i2c md 18 0

0000: 32 32 32 32 32 32 32 32 32 32 32 32 32 32 32 32

=> i2c mw 18 1 10

```

=> i2c mw 18 3 ef
=> i2c md 18 0
0000: 22 22 22 22 22 22 22 22 22 22 22 22 22 22 22 22
=> reset

```

U-Boot 2010.12-00063-g8669298-dirty (Jul 09 2011 - 14:37:56)

```

CPU0: P1025E, Version: 1.1, (0x80ec0311)
Core: E500, Version: 5.1, (0x80212051)
Clock Configuration:
  CPU0:400 MHz, CPU1:400 MHz,
  CCB:266.667 MHz,
  DDR:333.333 MHz (666.667 MT/s data rate) (Asynchronous), LBC:16.667 MHz
  QE:266.667 MHz
L1:  D-cache 32 kB enabled
     I-cache 32 kB enabled
Board: P1025RDB CPLD: V2.6 PCBA: V2.0
rom_loc: nor lower bank
SD/MMC : 4-bit Mode
eSPI : Enabled
I2C:  ready
SPI:  ready
DRAM:  Detected UDIMM(s)
DDR:  1 GiB (DDR3, 32-bit, CL=5, ECC off)
FLASH: 16 MiB
L2:   256 KB enabled
NAND:  32 MiB
MMC:   FSL_ESDHC: 0
Firmware 'Microcode version 0.0.1 for P1021 r1.0' for 1021 V1.0
QE: uploading microcode 'Microcode for P1021 r1.0' version 0.0.1
PCIe1: Root Complex of mini PCIe SLOT, no link, regs @ 0xffe0a000
PCIe1: Bus 00 - 00
PCIe2: Root Complex of PCIe SLOT, no link, regs @ 0xffe09000
PCIe2: Bus 01 - 01
Video: No radeon video card found!
In:   serial
Out:  serial
Err:  serial
Net:  eTSEC2 is in sgmi mode.
eTSEC1, eTSEC2, eTSEC3
Hit any key to stop autoboot:  0
=>

```

25.5.3 Uboot steps for overriding on-board switch to change NOR boot bank

1. First change to the correct I2C bus
 - => i2c dev 1
 - Setting bus to 1
2. A read of the input register will return the current state of the on-board switches.
 - => i2c md 18 0
 - 0000: 22 22 22 22 22 22 22 22 22 22 22 22 22 22 22 22

The register value shows that FBANK_SELECT on IO1 is one, thereby the switch SW4[8] is set to ON and the U-Boot is stored in the lower NOR boot bank now.

- Set you desired values for switches
 - =>i2c md 18 1 0
3. Next, set the IO ports as outputs.
 - => i2c mw 18 3 fd
 - Set the FBANK_SELECT IO1 bit to zero, thereby selecting the upper bank upon reset.
 4. A read will return the current over-written value that will be used for all subsequent resets.
 - => i2c md 18 0
 - 0000: 20 20 20 20 20 20 20 20 20 20 20 20 20 20 20 20
 5. Use U-Boot command to reset the system.
 - reset
 - if there is no uboot in the other bank of nor flash, system will not boot up.

NOTE

This value will be used until either the power is turned off, or the pins from the I2C device are tri-stated

26 Getting Started

This section describes how to boot the P1025RDB. The on-board flash memory is preloaded with a flash image from the factory. The on-board switches and jumpers are set to the factory defaults.

CAUTION

Avoid touching areas of integrated circuitry and connectors; static discharge can damage circuits.

WARNING

Turn OFF power during insertion and removal of any PCIe card.

26.1 External Cable Connections

Connect the serial port of the P1025RDB system and a host computer using an RS-232 cable. Also, connect the AC cable to the backside of the chassis.

26.2 Serial Port Configuration (PC)

Before powering up the P1025RDB, configure the serial port of the attached computer with the following values:

- Data rate: 115200 bps
- Number of data bits: 8
- Parity: None
- Number of Stop bits: 1
- Flow Control: Hardware/None

26.3 Power Up

Do not turn power on until all the cables are connected and the serial port is configured as described previously. Once done, power up the unit by pressing the power button on the backside of the chassis. A few seconds after power up, the U-Boot prompt should be received by the serial terminal program as illustrated in the example below:

```
U-Boot 2010.12-00063-g8669298-dirty (Jul 09 2011 - 14:37:56)
```

```
CPU0: P1025E, Version: 1.1, (0x80ec0311)
```

```
Core: E500, Version: 5.1, (0x80212051)
```

```
Clock Configuration:
```

```
  CPU0:533.333 MHz, CPU1:533.333 MHz,
```

```
  CCB:266.667 MHz,
```

```
  DDR:333.333 MHz (666.667 MT/s data rate) (Asynchronous), LBC:16.667 MHz
```

```
  QE:266.667 MHz
```

```
L1:  D-cache 32 kB enabled
```

```
  I-cache 32 kB enabled
```

```
Board: P1025RDB CPLD: V2.6 PCBA: V2.0
```

```
rom_loc: nor lower bank
```

```
SD/MMC : 4-bit Mode
```

```
eSPI : Enabled
```

```
I2C:  ready
```

```
SPI:  ready
```

```
DRAM:  Detected UDIMM(s)
```

```
DDR: 1 GiB (DDR3, 32-bit, CL=5, ECC off)
```

```
FLASH: 16 MiB
```

```
L2: 256 KB enabled
```

```
NAND: 32 MiB
```

```
MMC: FSL_ESDHC: 0
```

```
Firmware 'Microcode version 0.0.1 for P1021 r1.0' for 1021 V1.0
```

```
QE: uploading microcode 'Microcode for P1021 r1.0' version 0.0.1
```

```
PCIe1: Root Complex of mini PCIe SLOT, no link, regs @ 0xffe0a000
```

```
PCIe1: Bus 00 - 00
```

```
PCIe2: Root Complex of PCIe SLOT, no link, regs @ 0xffe09000
```

```
PCIe2: Bus 01 - 01
```

Getting Started

```
Video: No radeon video card found!  
In: serial  
Out: serial  
Err: serial  
Net: eTSEC2 is in sgmii mode.  
eTSEC1, eTSEC2, eTSEC3  
Hit any key to stop autoboot: 0  
=>
```

27 Revision History

Table 28 provides a revision history for this document.

Table 28. Document Revision History

Rev. Number	Date	Description
0.0	3/2011	First draft
0.1	3/2011	UEC1 PHY address changed from 4 to 6, refer to figure10, page15 Connect LA18 to SW3, so P1024E acts as an on PCIe 1, refer to table24,page35
2.0	8/2011	PCA9555 I2C connection changed from I2C2 to I2C1, refer to figure14, page19 Added J26 in table15, refer to page27, Added Table21 for single core frequency switch settings

How to Reach Us:

Home Page:

www.freescale.com

Web Support:

<http://www.freescale.com/support>

USA/Europe or Locations Not Listed:

Freescale Semiconductor, Inc.
Technical Information Center, EL516
2100 East Elliot Road
Tempe, Arizona 85284
1-800-521-6274 or
+1-480-768-2130
www.freescale.com/support

Europe, Middle East, and Africa:

Freescale Halbleiter Deutschland GmbH
Technical Information Center
Schatzbogen 7
81829 Muenchen, Germany
+44 1296 380 456 (English)
+46 8 52200080 (English)
+49 89 92103 559 (German)
+33 1 69 35 48 48 (French)
www.freescale.com/support

Japan:

Freescale Semiconductor Japan Ltd.
Headquarters
ARCO Tower 15F
1-8-1, Shimo-Meguro, Meguro-ku
Tokyo 153-0064
Japan
0120 191014 or
+81 3 5437 9125
support.japan@freescale.com

Asia/Pacific:

Freescale Semiconductor China Ltd.
Exchange Building 23F
No. 118 Jianguo Road
Chaoyang District
Beijing 100022
China
+86 10 5879 8000
support.asia@freescale.com

For Literature Requests Only:

Freescale Semiconductor
Literature Distribution Center
P.O. Box 5405
Denver, Colorado 80217
1-800 441-2447 or
+1-303-675-2140
Fax: +1-303-675-2150
LDCForFreescaleSemiconductor@hibbertgroup.com

Information in this document is provided solely to enable system and software implementers to use Freescale Semiconductor products. There are no express or implied copyright licenses granted hereunder to design or fabricate any integrated circuits or integrated circuits based on the information in this document.

Freescale Semiconductor reserves the right to make changes without further notice to any products herein. Freescale Semiconductor makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Freescale Semiconductor assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters which may be provided in Freescale Semiconductor data sheets and/or specifications can and do vary in different applications and actual performance may vary over time. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. Freescale Semiconductor does not convey any license under its patent rights nor the rights of others. Freescale Semiconductor products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Freescale Semiconductor product could create a situation where personal injury or death may occur. Should Buyer purchase or use Freescale Semiconductor products for any such unintended or unauthorized application, Buyer shall indemnify and hold Freescale Semiconductor and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Freescale Semiconductor was negligent regarding the design or manufacture of the part.

Freescale are trademarks or registered trademarks of Freescale Semiconductor, Inc. in the U.S. and other countries. All other product or service names are the property of their respective owners. The PowerPC name is a trademark of IBM Corp. and is used under license. RapidIO is a registered trademark of the RapidIO Trade Association. IEEE 1588 is a registered trademark of the Institute of Electrical and Electronics Engineers, Inc. (IEEE). This product is not endorsed or approved by the IEEE.

© Freescale Semiconductor, Inc., 2004- 2011. All rights reserved.