AN14402

Programming Multiple Targets in Parallel by MCU-Link and LinkServer Rev. 1.0 — 18 October 2024 Application note

Document information

Information	Content
Keywords	AN14402, MCU-Link, LinkServer, Program Multiple Targets
Abstract	This document introduces how to program multiple targets in parallel on a Windows machine, resulting in a simpler and time-saving task.



Overview 1

Programming multiple targets in a row is generally a complex and time-consuming task. In this application note, MCU-Link and LinkServer, which is both our low-cost debugging solution is introduced to program the multiple targets in parallel on a Windows machine. It results in a simpler and time-saving task.

2 System architecture

Let us assume that there are three targets to be programmed at the same time.

Figure 1 shows the system diagram to program multiple targets in parallel. One MCU-Link is needed for every target.

MCU-Link is a powerful and cost-effective debug probe that can be used seamlessly with MCUXpresso-IDE. MCUXpresso for Visual Studio Code is compatible with the third-party IDEs that support the CMSIS-DAP protocol. MCU-Link includes a USB to UART bridge feature (VCOM) to provide a serial connection between the target MCU and a host computer.

In this system, LinkServer on the host computer handles three MCU-Links in parallel. LinkServer is a utility for launching and managing GDB servers for NXP debug probes, which also provide a command-line target flash programming capability.



Create binary image in MCUXpresso IDE 3

The binary image generated by MCUXpresso IDE is downloaded to each target. To generate the binary image after building, uncomment out

arm-none-eabi-objcopy -v -O binary "\${BuildArtifactFileName}" \${BuildArtifactFileBaseName}.bin in the post-build settings as shown in Figure 2.

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be filter text	Settings	
Resource Builders C/C++ Build Build Variables Environment Logging MCU settings Settings Tool Chain Editor C/C++ General MCUXpresso Config Tools Project Natures Project References Run/Debug Settings Task Tags Validation	Configuration: Debug [Active]	Manage Configurations Artifact Binary Parsers Frror Parsers r
	Performing post-build steps	~
?		Apply and Close Cancel
		222.057

You can confirm that the binary image is generated from the execution file as shown in Figure 3.

ϳ Installed SDKs 🔲 Properties 🦹 Problems 🖷 Progress 📮 Console 🗙 🖉 Terminal 🗟 Image Info 🖳 Debugger Console 🧏 Offline Peripherals 🗱				
CDT Build Console [evkbmimxrt1170_hello_world_demo_cm7]				
14:47:03 **** Incremental Build of configuration Debug for project evkbmimxrtll70 hello world demo cm7 ****				
make -r -j20 all				
<pre>make[1]: Nothing to be done for 'main-build'.</pre>				
Performing post-build steps				
arm-none-eabi-size "evkbmimxrtll70_hello_world_demo_cm7.axf"; arm-none-eabi-objcopy -v -0 binary "evkbmimxrtll70_hello_world_d				
text data bss dec hex filename				
34160 4 8500 42664 a6a8 evkbmimxrtl170_hello_world_demo_cm7.axf				
copy from `evkbmimxrtl170_hello_world_demo_cm7.axf' [elf32-littlearm] to `evkbmimxrtl170_hello_world_demo_cm7.bin' [binary]				
14:47:04 Build Finished. 0 errors, 0 warnings, (took 532ms)				
aaa-057347				
Figure 3. Binary image generated from ARM executable format				

4 LinkServer script

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Application note

Some scripts are needed to handle multiple MCU-Link targets parallelly by LinkServer. In this section, two batch files (*program_all_probes.bat* and *program_probe.bat*) associated with this application note are explained.

At first, all probes connected to the host computer are shown below by a low-level command, called probelist:

```
C:\nxp\LinkServer_1.5.30\binaries>redlinkserv --commandline
redlink>probelist
Index = 1
Manufacturer = NXP Semiconductors
Description = MCU-LINK on-board (r0E2) CMSIS-DAP V3.133
```

```
Serial Number = FDNX2FVTNFTVJ
VID:PID = 1FC9:0143
Path = 0002:000a:00
redlink>exit
```

To identify a probe among multiple probes on a host computer, use the corresponding serial number of the probe.

A target can be programmed by identifying the probe. An example command is given below:

Note: --erase-all can be omitted for optimization.

In the batch file *program_all_probes.bat*, probelist is used to get the serial number of the probes and the batch file *program_probe.bat* is started as a new process.

An example script is given below:

You can erase, program, and verify the flash in the identified target by the batch file *program_probe.bat*. An example script is given below:

```
%3/LinkServer flash --probe %1 MIMXRT1176xxxxx:MIMXRT1170-EVKB load --addr 0x30000000 %2 --erase-
all > probe_%1.log 2>&1
%3/LinkServer flash --probe %1 MIMXRT1176xxxxx:MIMXRT1170-EVKB verify --addr 0x30000000 %2
>> probe_%1.log 2>&1
exit 0
```

5 Running the demo

To run the demonstration, perform the following steps:

- 1. Install LinkServer version 1.5.30 on the host computer.
- Connect a USB cable between the host computer and the OpenSDA USB port on an arbitrary number of RT1170-EVKB.
- 3. Run the batch file program_all_probes.bat.

All probes are automatically detected. New windows are opened as the same number of multiple probes shown in <u>Figure 4</u>.

An example script detecting the connected multiple probes is given below:

```
>program_all_probes.bat
Probe F0NU2JRCKEWYT found.
Probe FDNX2FVTNFTVJ found.
Probe 0P0NJTEBAJR1G found.
```



Figure 4. New windows are opened as the same number of multiple probes

Windows disappear automatically after erase, program, and verify operations. The logs are saved in the ./ probe_{serial number}.log file. Verify succeeds if the demo runs correctly.

Observation: In the experiment, it is observed that the processing time is about three times faster than serial programming, when three targets are connected as shown in <u>Table 1</u>:

Table 1. Serial programming versus Parallel programming

Programming	Processing Time [s]			
Serial	424			
Parallel	150			

6 Conclusion

MCU-Link and LinkServer can be used to program multiple targets in parallel. It can be extended to other platforms like MacOS or Linux.

7 Note about the source code in the document

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8 Revision history

Table 2 summarizes the revisions to this document.

Table 2. Revision history

Document ID	Release date	Description
AN14402 v.1.0	18 October 2024	Initial public release

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Document feedback Date of release: 18 October 2024 Document identifier: AN14402